



MATEKSYS

FLIGHT CONTROLLER H743-WING

QUICK START GUIDE

MCU: STM32H743VIT6, 480MHz, 2MB Flash

IMU: MPU6000 (SPI1) & ICM20602 (SPI4)

Baro: DPS310 (I2C2)

OSD: AT7456E (SPI2)

Blackbox: MicroSD card slot (SDIO)

7x Uarts (1,2,3,4,6,7,8) with built-in inversion

13x PWM outputs

2x I2C

1x CAN

6x ADC (VBAT, Current, RSSI, Analog AirSpeed, VB2, CU2)

1x SPI3 breakout

Switchable Dual Camera Inputs

Switchable 5V/9V(12V) for Camera/VTX

9~36V DC IN (3~8S LiPo)

High-precision Current Sense 132A Range

BEC 5V 2A for FC

BEC 9V 2A for camera/VTX, 12V option

BEC Vx 8A cont. 10A burst for servos, 5V, 6V or 7.2V option

LDO 3.3V 200mA

ArduPilot hwdef: MATEKH743

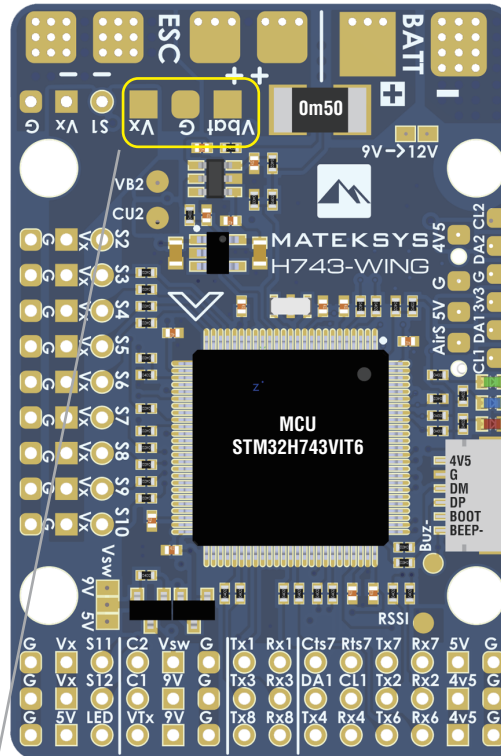
INAV: MATEKH743



LAYOUT

+ & - : Battery & ESC power pads, 9-36V DC(3-8S Lipo).

Battery Voltage Sensor: 1K10K
Current Sensor: 132A, 3.3V ADC
Current Sense resistor: 60A continuous, 132A burst.



S1-S12, LED: PWM1-PWM13

Vx: BEC 5V/6V/7.2V for servos, Default is 5V
8A cont. Max.10A



5V: onboard BEC 5V 2A cont. Max.3A
9V: onboard BEC 9V 2A cont. Max.3A,
*** 9V rise to 12V if "9V->12V" jumper is bridged.
G: Ground

Vsw: 5V/9V selection
*** ON/OFF can be switched via ArduPilot Relay or Modes/USER1 (INAV)
*** Max.1A load on this pad. (Default ON)
*** Vsw jumper one or the other must be bridged

C1: Camera-1 video IN (Default)
C2: Camera-2 video IN
*** C1/C2 can be switched via ArduPilot Relay or Modes/USER2 (INAV)

VTX: Video OUT for Video Transmitter

ArduPilot tips

on board battery voltage: BATT_VOLT_PIN 10, BATT_VOLT_MULT 11
on board current sensor: BATT_CURR_PIN 11, BATT_AMP_PERVLT 40

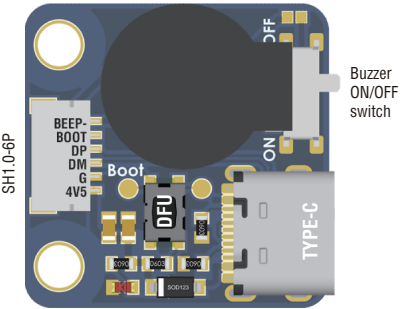
VB2: Voltage divider 1K10K, Max.36V supported
BATT2_VOLT_PIN 18, BATT2_VOLT_MULT 11
CU2: for external current sensor, 0-3.3V
BATT2_CURR_PIN 7

9V->12V 9V rise to 12V

AirS: Analog Airspeed sensor (0-6.6V)
1: 1 voltage divider built-in
ARSPD_PIN 4

DA2 & CL2: I2C2
DA1 & CL1: I2C1
3.3: LD03.3V 200mA

LED 0: Blue, FC Status
LED 1: Green, FC Status
LED 3.3: Red, 3.3V Status



Rssi: Analog RSSI, RSSI_ANA_PIN 8 (ArduPilot)

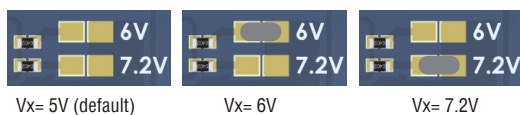
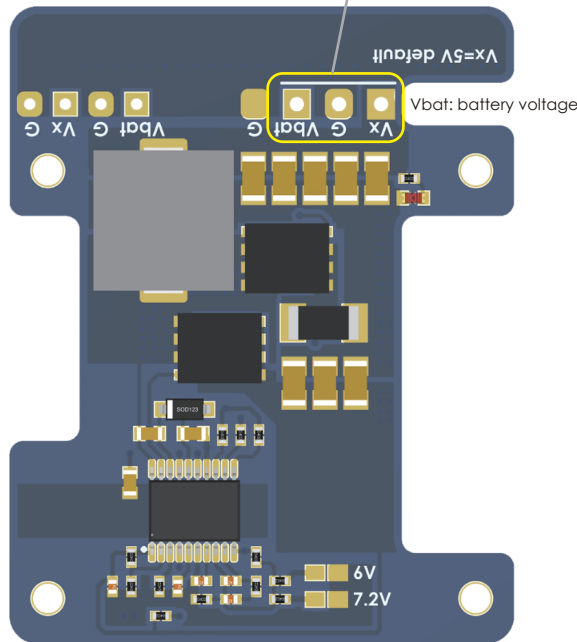
4V5: 4.4-4.8V, Max.500mA
*** the voltage is also supplied when connecting via USB

TX1/RX1: UART1, TX3/RX3: UART3
TX8/RX8: UART8, TX4/RX4: UART4

TX7/RX7: UART7
CTS/Rts7: UART7_CTS/RTS for ArduPilot Telem1

TX2/RX2: UART2
DA1 & CL1: I2C1, for compass

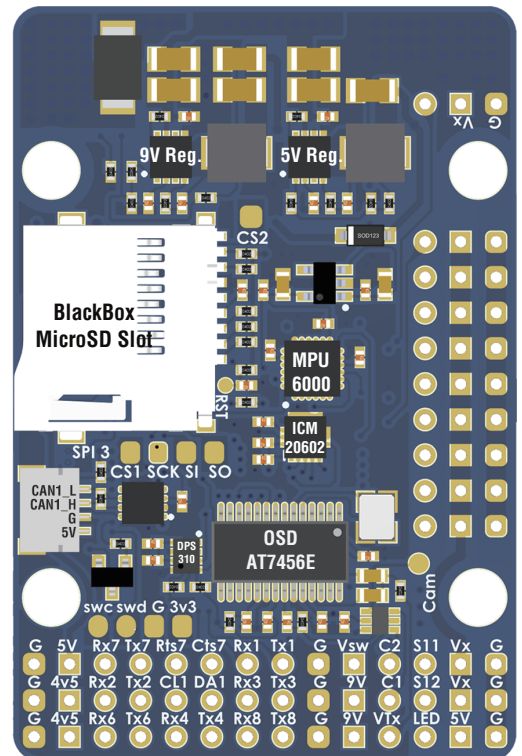
RX6: UART6-RX for Serial_RX by default
PPM share RX6 pad
TX6: UART6-TX



SPI3 breakout

CAN Port
SH1.0-4P connector

SWC & SWD: STlink

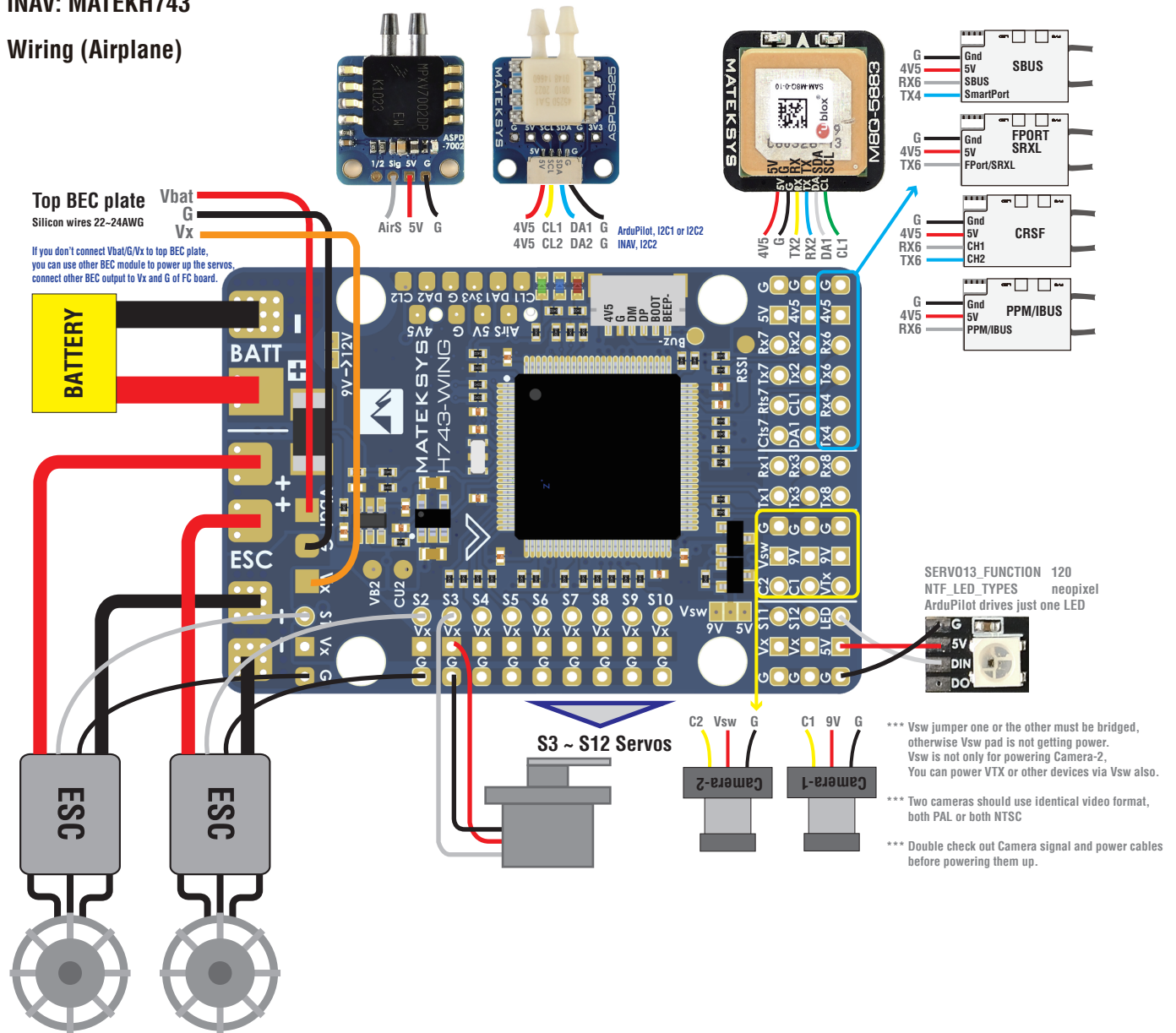


Size: 54x36x13mm
Weight: 30g w/ top and bottom plate & USB extender
Holes: Φ 4mm, 30.5mm mounting
M3 Silicon Grommets included

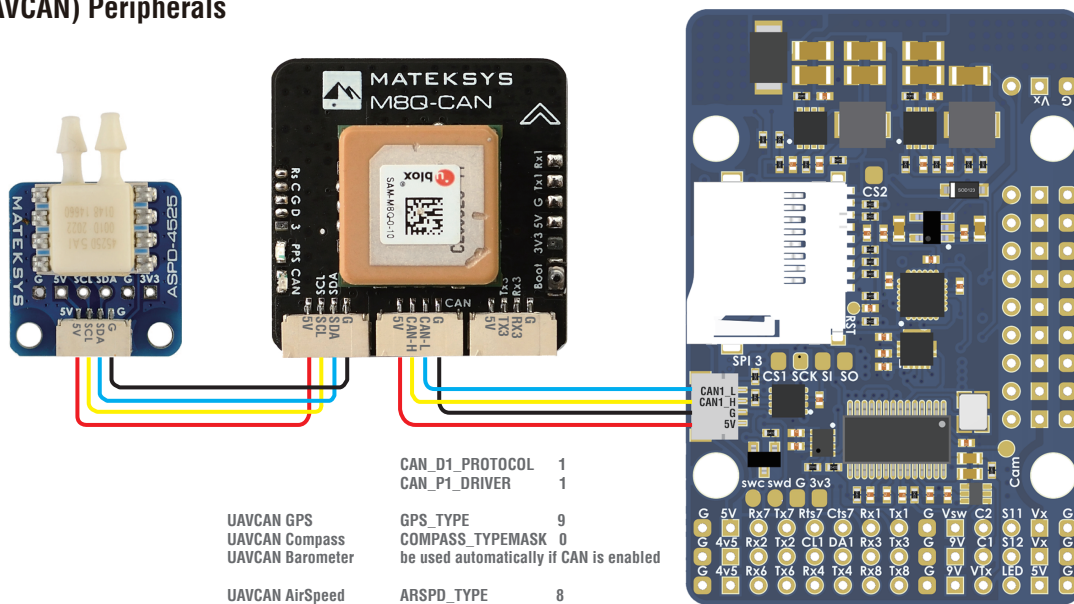
ArduPilot: MATEKH743

INAV: MATEKH743

Wiring (Airplane)

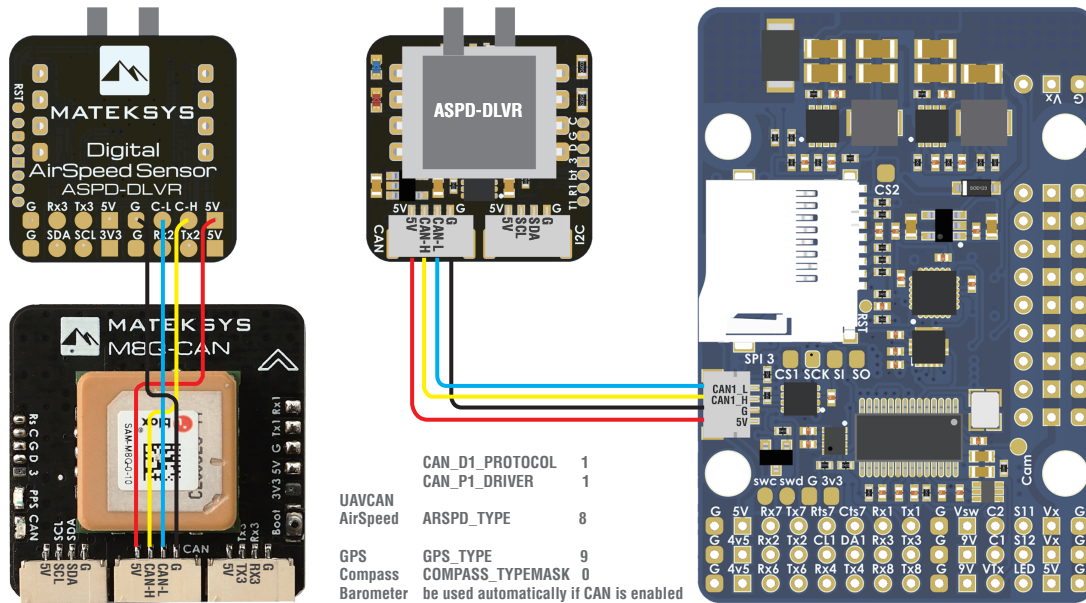


CAN (UAVCAN) Peripherals

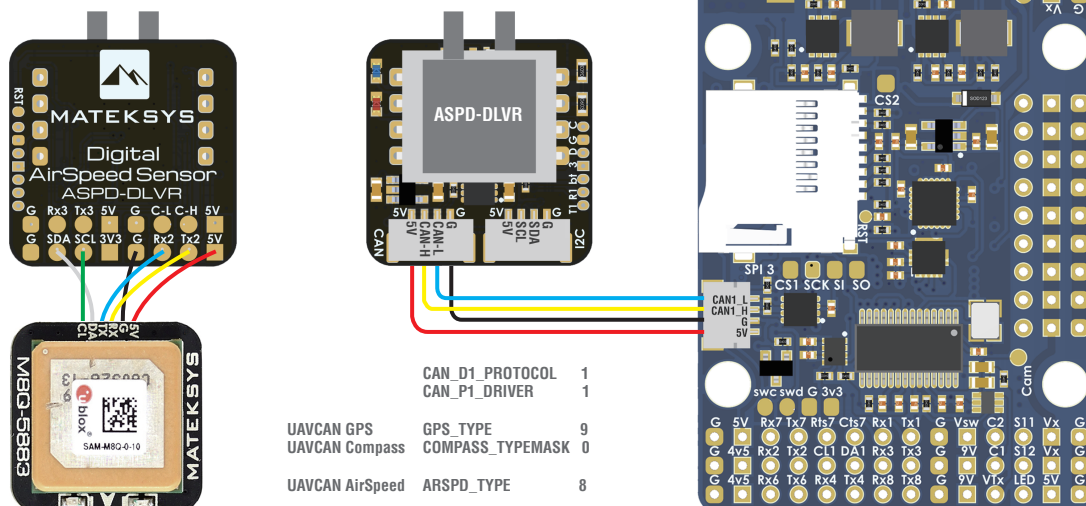


CAN (UAVCAN) Peripherals

2x CAN Peripherals in parallel



ASPD-DLVR CAN Node



M8Q-CAN Node, ASPD-DLVR I2C mode

